

# PCAN-Flash

Windows-Software for Flashing  
Firmware via CAN

## Operation Instructions



Document version 1.1.0 (2015-11-11)

**PEAK**  
System

## Products taken into account

Product Name	Model	Part number
PCAN-Flash	from version 2.0	
PCAN-Router	with D-Sub connectors with Phoenix connector opto-decoupled with D-Sub connectors	IPEH-002210 IPEH-002210-P IPEH-002211
PCAN-Router FD	with D-Sub connectors with Phoenix connector	IPEH-002214 IPEH-002215
PCAN-Router DR		IPEH-002213
PCAN-RS-232		IPEH-002100
PCAN-GPS		IPEH-002110
PCAN-Router Pro		IPEH-002212
PCAN-MIO	Industrial Automotive	IPEH-002187 IPEH-002187-A (from serial number 100)
PCAN-MicroMod	module with evaluation board	IPEH-002080 + IPEH- 002082
MU-Thermocouple1 CAN		IPEH-002205
PCAN-USB FD		IPEH-004022
PCAN-USB Pro FD		IPEH-004061

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# 1 Introduction

PCAN-Flash is a Windows program for flashing firmware via CAN. Thus, the firmware of several hardware products from PEAK-System can be updated.

These instructions cover the sequence of the flash process, from the preparation of the hardware to the actual flashing of the firmware with PCAN-Flash.

Microcontroller hardware being supported by PCAN-Flash:

- └ PCAN-Router
- └ PCAN-Router FD
- └ PCAN-Router DR
- └ PCAN-RS-232
- └ PCAN-GPS
- └ PCAN-Router Pro
- └ PCAN-MicroMod
- └ PCAN-MIO (from serial number 100)
- └ MU-Thermocouple1 CAN

CAN interfaces being supported by PCAN-Flash:

- └ PCAN-USB FD
- └ PCAN-USB Pro FD

## 1.1 System Requirements

Besides the hardware that will be equipped with new firmware, you need the following:

- └ Computer with Windows 10, 8.1, 7, or Vista (32/64-bit)
- └ CAN interface of the PCAN series installed in/attached to the computer
- └ CAN cabling between the CAN interface and the hardware with proper termination ( $120\ \Omega$  on each end of the CAN bus, not applicable to PCAN-USB FD and PCAN-USB Pro FD)

## 2 Preparing the Microcontroller Hardware

 **Note:** If you want to flash a CAN interface (PCAN-USB FD, PCAN-USB Pro FD), skip this chapter and continue with chapter 3 on page 15.

In order to equip the microcontroller hardware with new firmware via CAN, the CAN bootloader must be activated when powering on. Different preparations are necessary depending on the hardware.

 **Note:** If your hardware works with configurations, those configurations that are currently on the hardware are going to be invalid after a firmware update and therefore will not be usable anymore. Make sure in advance that the configurations are available on your PC so that you are able to transfer them to your hardware again later on.

 Perform the following steps for preparation of your hardware:

1. Switch the device off by disconnecting it from the power supply.
2. Perform the necessary modification of your hardware. It is described in the corresponding section (see table). Before the modification, remember the initial state, in order to be able to restore it after the firmware update.

Hardware	Modification	Section
PCAN-Router	High level at Boot_CAN	2.1 on page 9
PCAN-Router FD	High level at Boot	2.2 on page 10
PCAN-Router DR	Rotary switch "Bitrate" on F	2.3 on page 11
PCAN-RS-232	High level at Boot_CAN	2.4 on page 11
PCAN-GPS	High level at Boot_CAN	2.4 on page 11
PCAN-Router Pro	ID rotary switch on F	2.5 on page 12
PCAN-MIO	ID rotary switch on F	2.6 on page 13
PCAN-MicroMod	(none)	2.7 on page 13
MU-Thermocouple1 CAN	(none)	2.8 on page 14



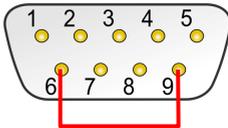
**Tip:** On some devices, the flash mode can alternatively be activated by software so that the hardware modification can be omitted. See corresponding notes in the section for the device.

3. Connect the CAN bus of the hardware with a CAN interface connected to the computer. Pay attention to the proper termination of the CAN cabling (2 x 120 Ω).
4. Switch on the hardware by applying a voltage supply.

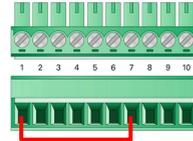
## 2.1 PCAN-Router

### Preparation

Establish a connection between “Boot CAN1” and “+U<sub>b1</sub>” or “+U<sub>b</sub>” at the connectors of the PCAN-Router.



Connection at D-Sub connector CAN1 between the pins 6 (Boot CAN1) and 9 (+U<sub>b1</sub>)



Connection at the screw terminal strip between terminals 1 (+U<sub>b</sub>) and 7 (Boot CAN1)

This preparation later applies the “Boot CAN1” connection with a high level.

### Indicator for Flash Mode

LED	State	Color
CAN1	on or blinking	orange
CAN2	on	orange

### Additional Information

Uploading firmware via CAN bus 2 is not possible.

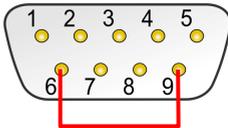


**Attention!** Risk of short circuit! A CAN cable with D-Sub connectors must not have a connection on pin 6, as it can be seen on 1:1 cables, for example. At other CAN nodes (e.g. a CAN interface of the PCAN series) this line may be applied to the mass. Damage or destruction of the electronics is a possible consequence.

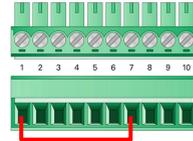
## 2.2 PCAN-Router FD

### Preparation

Establish a connection between “Boot” and the power supply (“U<sub>b1</sub>”, “U<sub>b2</sub>”, or “U<sub>b</sub>”) at the connectors of the PCAN-Router FD.



Connection at D-Sub connector CAN1  
between the pins 6 and 9



Connection at the screw terminal  
strip  
between terminals 1 and 7

This measure later applies the “Boot” connection with a High level.

### Indicator for Flash Mode

LED	State	Color
CAN1	blinking	orange
CAN2	on	orange

### Additional Information



**Attention!** Risk of short circuit! A CAN cable with D-Sub connectors must not have a connection on pin 6, as it can be seen on 1:1 cables, for example. At other CAN nodes (e.g. a CAN interface of the PCAN series) this line may be applied to the mass. Damage or destruction of the electronics is a possible consequence.

## 2.3 PCAN-Router DR

### Preparation

On the front, turn the rotary switch „Bitrate“ to setting F.

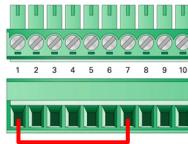
### Indicator for Flash Mode

LED	State	Color
Status	off	
CAN 1	blinking	orange
CAN 2	on	orange

## 2.4 PCAN-RS-232 and PCAN-GPS

### Preparation

At the connectors of the module, establish a connection between “Boot CAN” and “U<sub>b</sub>”.



Connection at the screw terminal strip  
between terminals 1 and 7

This preparation later applies the “Boot CAN” connection with a high level.

### Indicator for Flash Mode

LED PCAN-RS-232	State	Color
Status	blinking	orange
LED PCAN-GPS		
Status 1	blinking	orange
Status 2	on	orange



## Additional Information

After an update of the standard firmware, the “ $\mu$ C Status” LED blinks with increased frequency (2 Hz) indicating that no configuration is available. Re-transfer your configuration(s) to the PCAN-Router Pro with the PPCAN-Editor.

## 2.6 PCAN-MIO

### Preparation

Turn the rotary switch for the module ID to F.

### Indicator for Flash Mode

LED	State	Color
Status	blinking	red and green alternating

### Additional Information

A firmware update via CAN is only possible with PCAN-MIO modules from serial number 100. Older hardware can be provided with new firmware at PEAK-System on request.

## 2.7 PCAN-MicroMod

### Preparation

The PCAN-MicroMod can only be set to flash mode by PCAN-Flash just before the flash process. A modification of the hardware is not needed.

### Indicator for Flash Mode

LED	State	Color
Status	blinking	red

## Additional Information

After an update of the firmware, the LED on the PCAN-MicroMod blinks with increased frequency (2 Hz) indicating that no configuration is available. Re-transfer your configuration to the PCAN-MicroMod with the Windows program PCAN-MicroMod Configuration.

## 2.8 MU-Thermocouple1 CAN

### Preparation

The measuring unit MU-Thermocouple1 CAN can only be set to flash mode by PCAN-Flash just before the flash process. A modification of the hardware is not needed.

### Indicator for Flash Mode

LED	State	Color
Status	blinking	red

## 3 Preparing the software

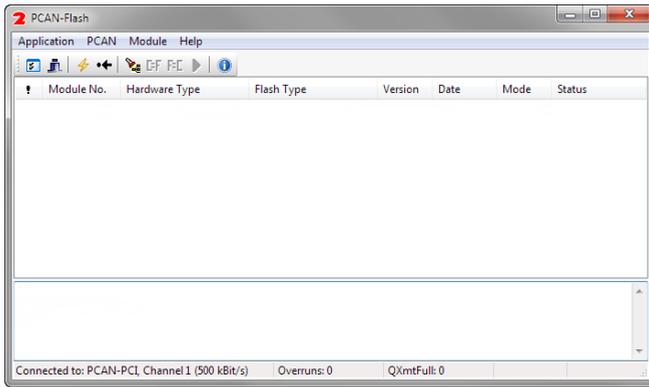
PCAN-Flash must be started from a data carrier which is also writable, otherwise the program's configuration (`PcanFlash.ini` file) cannot be saved. The program doesn't work properly if it is run from a DVD. This is reflected, for example, by an error message when selecting a CAN connection.

Make sure that the `PCAN-Flash` directory is located on a local hard disk, for example, (if necessary, copy it from DVD) and that there are write permissions in the directory, and execute PCAN-Flash from there.

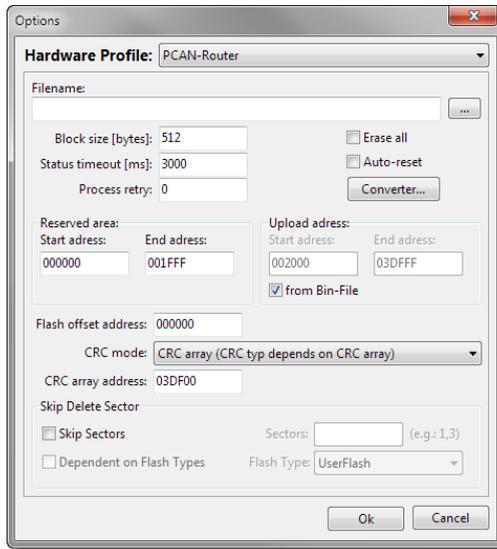
## 4 Flashing the Firmware

▶ Do the following to flash the firmware for your hardware:

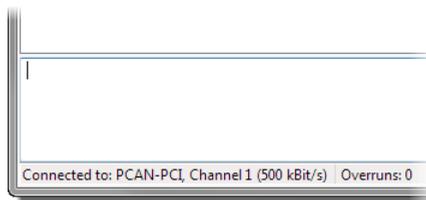
1. Run the program `PcanFlash.exe` under Windows from the local hard drive.



2. Click on the  (Options) button in order to call up the dialog box.
3. From the **Hardware Profile** dropdown list, select your hardware (here: PCAN-Router).

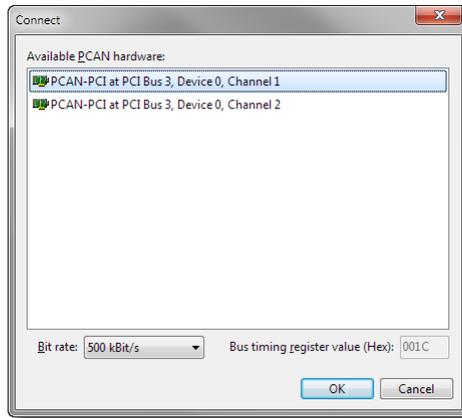


4. Click on the ... button next to the **File name** field in order to select the desired firmware file (\*.bin) to be flashed.
5. Click on the **OK** button.
6. Make sure that the PCAN-Flash program is connected with 500 kbit/s to the available CAN interface at the computer.



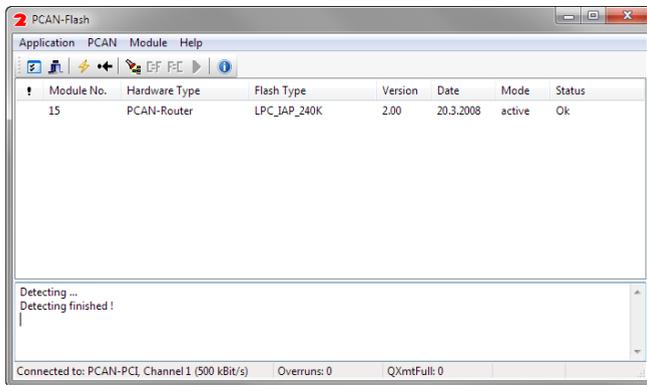
PCAN-Flash: Display of a connection in the status bar on the bottom.

If not, click the ⚡ (Connect) button in order to change the selection in the according dialog box.



7. **Only CAN interfaces:** Select the menu command **PCAN > Set USB to flash mode**.
8. Click the  (Detect) button in order to detect the hardware connected to the CAN bus.

An entry for your hardware appears in the main window (here: PCAN-Router).



9. Select the entry for your hardware.



**Tip:** On some devices, here is the point where you can start the CAN bootloader alternatively with PCAN-Flash instead by hardware modification. To do so, click the **EF** (Activate module) button.

10. Click the **▶** (Program) button in order to start uploading the new firmware to the PCAN-Router.

Observe the status indication at the bottom of the window. The process was successful if the last message to appear is "Flashing of module(s) finished!".

11. Disconnect the power supply from your hardware or the CAN interface from the PC.
12. Undo the modification of the hardware that you've done before in chapter 2.

You can now use the hardware with the new firmware.